

BANKING AND MANAGEMENT INFORMATION SYSTEM AUTOMATION

Luis Andrade, Amílcar Sernadas

*Caixa, Sistemas de Informação
Rua Padre António Vieira, 32, 8º andar, 1100 Lisboa, Portugal
IST
Av. Rovisco Pais, 1000 Lisboa, Portugal*

Abstract: An Object Oriented Model for large scale projects is proposed, with a formal framework for inheritance, dynamic classification, object specification decomposition, composition of objects (aggregation) and object single and joint behaviour semantics. The model is based on a full concurrent community of objects. It is advocated that such a model enhances concurrency, improves abstraction, refinement and reusability, explains different forms of inheritance and gives a concise semantic for aggregation and exception handling.

Keywords: Concurrency, Events, Inheritance, Interaction, Invariants, Object, Synchronisation

1. INTRODUCTION

The critical aspects of today Banking Management Information Systems are, among others: time to market (dealing with components' development and re-use), evolution (volatility of business requirements), requirements' conformance (take decisions upon correct information), large-scale and complex systems, parallelism, maintenance, robustness and security. Product distribution, management information systems and decision support systems are typical banking applications facing this problems.

Another problem companies are facing today is that they must have a technology migration path planning from current traditional systems to future open systems. An encapsulation mechanism to hide "legacy systems" is essential to guaranty a smooth transition, coping with the business support extensibility.

This paper introduces a rigorous approach, derived from GNOME (Ehrich *et al.*, 1993; Saake *et al.*, 1993), addressing, among other things, normative and non-

normative behaviour, inheritance and composition and decomposition.

Effort was made to introduce a well defined semantic, in order to fulfil the following desirable characteristics for object-oriented approaches: *method composition and extension, dynamic classification, direct object interaction and event broadcast, behaviour inheritance, compositionality and encapsulation*. Some properties relevant to wider software engineering were also included, namely: the ability to specify concurrent behaviour and properties; the ability to deal with non-normative behaviour (*exception handling*); allowing the systematic refinement of specifications to code, preferably in a compositional manner.

According to these principles, an **Information System** is treated as a *collection of interacting concurrent objects* where the object notion is the unification of the system constituents.

An **object** is an abstraction with a persistent *identity*, a *public interface* defined by the provided services and recognised events (only way to interact with the object, accessing its internal state) and an *internal body*, including

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Fault Detection and Diagnosis in Industrial Systems L.H. Chiang,E.L. Russell,R.D. Braatz,2012-12-06 Early and accurate fault detection and diagnosis for modern chemical plants can minimise downtime increase the safety of plant operations and reduce manufacturing costs The process monitoring techniques that have been most effective in practice are based on models constructed almost entirely from process data The goal of the book is to present the theoretical background and practical techniques for data driven process monitoring Process monitoring techniques presented include Data driven methods principal component analysis Fisher discriminant analysis partial least squares and canonical variate analysis Analytical Methods parameter estimation observer based methods and parity relations Knowledge based methods causal analysis expert systems and pattern recognition The text demonstrates the application of all of the data driven process monitoring techniques to the Tennessee Eastman plant simulator demonstrating the strengths and weaknesses of each approach in detail This aids the reader in selecting the right method for his process application Plant simulator and homework problems in which students apply the process monitoring techniques to a non trivial simulated process and can compare their performance with that obtained in the case studies in the text are included A number of additional homework problems encourage the reader to implement and obtain a deeper understanding of the techniques The reader will obtain a background in data driven techniques for fault detection and diagnosis including the ability to implement the techniques and to know how to select the right technique for a particular application

CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume VI Heinz D. Unbehauen,2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and Decision Makers and NGOs Proceedings of the ... American Control Conference ,1998

Control in Robotics and Automation Bijoy K. Ghosh,T. J. Tarn,Ning Xi,1999-04-09 Microcomputer technology and micromechanical design have contributed to recent rapid advances in Robotics Particular advances have been made in sensor technology that allow robotic systems to gather data and react intelligently in flexible manufacturing systems The analysis and recording of the data are vital to controlling the robot In order to solve problems in control and planning for a Robotic system it is necessary to meet the growing need for the integration of sensors in to the system Control in Robotics and Automation addresses this need This book covers integration planning and control based on prior knowledge and real time sensory information A new task oriented approach to sensing planning and control introduces an event based method for system

design together with task planning and three dimensional modeling in the execution of remote operations Typical remote systems are teleoperated and provide work efficiencies that are on the order of ten times slower than what is directly achievable by humans Consequently the effective integration of automation into teleoperated remote systems offers potential to improve remote system work efficiency The authors introduce visually guided control systems and study the role of computer vision in autonomously guiding a robot system Sensor Based Planning and Control in an Event Based Approach Visually Guided Sensing and Control Multiple Sensor Fusion in Planning and Control System Integration and Implementation Practical Applications **Proceedings of the ... Annual Conference of the IEEE Industrial Electronics Society** IEEE Industrial Electronics Society. Conference,2003 **Advanced Control and Supervision of Mineral Processing Plants** Daniel Sbárbaro,René Del Villar,2010-08-20 Advanced Control and Supervision of Mineral Processing Plants describes the use of dynamic models of mineral processing equipment in the design of control data reconciliation and soft sensing schemes through examples it illustrates tools integrating simulation and control system design for comminuting circuits and flotation columns Coverage is given to the design of soft sensors based on either single point measurements or more complex measurements like images Issues concerning data reconciliation and its employment in the creation of instrument architecture and fault diagnosis are surveyed In consideration of the widespread use of distributed control and information management systems in mineral processing the book describes the platforms and toolkits available for implementing such systems Applications of the techniques described in real plants are used to highlight their benefits information for all of the examples together with supporting MATLAB code can be found at www.springer.com 978 1 84996 105 9 **Irish Signals and Systems Conference** ,2006 *Structural Analysis and Design* ,1998 Power Plants and Power Systems Control 2000 J.-P. Waha,2000 Paperback With the decentralisation and liberalisation of the electrical energy system in Europe the network companies as well as the power plant companies will be faced with many new emerging technical problems This Proceedings contains papers presented at the IFAC 2000 Symposium on Power Plants and Power Systems Control this symposium aimed to provided international experts with a platform to discuss the challenges facing the power plant industry and to present solutions developed in countries who have previously encountered these new paradigms of grid control One of the main aims of the symposium was to promote a better knowledge of the behaviour of the power plants and power systems with the ultimate goal of an efficient flexible and secure operation coupled with a high level of service to their customers Advances in Soft Computing Rajkumar Roy,1999 Advances in Soft Computing contains the most recent developments in the field of soft computing in engineering design and manufacture The book comprises a selection of papers that were first presented in June 1998 at the 3rd On line World Conference on Soft Computing in Engineering Design and Manufacturing Amongst these are four invited papers by World renowned researchers in the field Soft computing is a collection of methodologies which aim to exploit tolerance for imprecision uncertainty and partial truth to achieve tractability robustness

and low solution cost The area of applications of soft computing is extensive Principally the constituents of soft computing are fuzzy computing neuro computing genetic computing and probabilistic computing The topics in this book are well focused on engineering design and manufacturing This broad collection of 43 research papers has been arranged into nine parts by the editors These include Design Support Systems Intelligent Control Data Mining and New Topics in EA basics The papers on evolutionary design and optimisation are of particular interest Innovative techniques are explored and the reader is introduced to new highly advanced research results The editors present a unique collection of papers that provide a comprehensive overview of current developments in soft computing research around the world

Proceedings of the First Workshop on Robot Motion and Control, 1999 This collection of articles from the First Workshop on Robot Motion and Control includes articles on control modelling and parameter identifications robot control techniques and path and trajectory planning

Proceedings of the ... SICE Annual Conference Keisoku Jidō Seigyo Gakkai (Japan). Gakujutsu Kōenkai, 2004 Vehicle Lateral Control for Driver Assistance and Automated Driving Kai-Ten Feng, 2000

7th International Workshop on Advanced Motion Control 2002, 2002 *Proceedings*, 2004 *Identification and Robust Control of Linear Parameter-varying Systems* Lawton Hubert Lee, 1997 *IEEE International Symposium on Industrial Electronics Proceedings*, 2001

Intelligent Systems and Automation Lotfi Beji, Samir Otmane, Azgal Abichou, 2009-03-09 The aim of CISA 09 is to present the latest research and application results emerging from new research and technological developments of complex systems and intelligent machines acting on known or unknown virtual or real environments in an autonomous way or in cooperation with humans This field requires skills in automation and control perception of the environment human computer interfaces mechanics and design simulation etc It also aims at encouraging scientific cooperation between North and South and promoting scientific exchanges through a durable event

Component and Systems Diagnostics, Prognosis, and Health Management, 2001 Subspace Methods for System Identification Tohru Katayama, 2005-10-11 An in depth introduction to subspace methods for system identification in discrete time linear systems thoroughly augmented with advanced and novel results this text is structured into three parts Part I deals with the mathematical preliminaries numerical linear algebra system theory stochastic processes and Kalman filtering Part II explains realization theory as applied to subspace identification Stochastic realization results based on spectral factorization and Riccati equations and on canonical correlation analysis for stationary processes are included Part III demonstrates the closed loop application of subspace identification methods Subspace Methods for System Identification is an excellent reference for researchers and a useful text for tutors and graduate students involved in control and signal processing courses It can be used for self study and will be of interest to applied scientists or engineers wishing to use advanced methods in modeling and identification of complex systems

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