

World Scientific Series in Robotics and Intelligent Systems – Vol. 26

ACTIVE SENSORS FOR LOCAL PLANNING IN MOBILE ROBOTICS

PENELOPE PROBERT SMITH



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Active Sensors For Local Planning In Mobile Robotics

Alejandra Barrera



Active Sensors For Local Planning In Mobile Robotics:

Active Sensors For Local Planning In Mobile Robotics Penelope Probert Smith, 2001-12-05 This book describes recent work on active sensors for mobile robots. An active sensor interacts with its surroundings to supply data on demand for a particular function, gathering and abstracting information according to need rather than acting as a generic data gatherer. Details of the physical operation are hidden. The book deals mainly with active range sensors which provide rapid information for local planning, describing extraction of two-dimensional features such as lines, corners, and cylinders to reconstruct a plan of a building. It is structured according to the physical principles of the sensors, since to a large extent these determine the function of the sensors and the methods of processing. Recent work using sonar, optoelectronic sensors, and radar is described. Sections on vision and on sensor management develop the idea of software adaptation for efficient operation in a changing environment.

Evolutionary Robotics: From Algorithms To Implementations Ling-feng Wang, Kay Chen Tan, Chee-meng Chew, 2006-07-17 This invaluable book comprehensively describes evolutionary robotics and computational intelligence and how different computational intelligence techniques are applied to robotic system design. It embraces the most widely used evolutionary approaches with their merits and drawbacks, presents some related experiments for robotic behavior evolution, and the results achieved, and shows promising future research directions. Clarity of explanation is emphasized such that a modest knowledge of basic evolutionary computation, digital circuits, and engineering design will suffice for a thorough understanding of the material. The book is ideally suited to computer scientists, practitioners, and researchers keen on computational intelligence techniques, especially the evolutionary algorithms in autonomous robotics at both the hardware and software levels.

Mobile Robotics in Healthcare Nikos Katevas, 2001 The text presents the conclusions of four years' joint work of 12 European laboratories on mobile robotics technology for healthcare services. The book bridges the human factors and the demands of real-life applications to the achievements of the robotics technology. It is organized in 15 chapters, analyzing topics covering all the related fields and including but not limited to user application requirements, human-machine interfacing, mobile robots and mobile manipulators, control architectures, navigation, and sensing strategies, and robot-smart building interconnection. It also provides technical details and hints to the reader on how to address real-life problems. The book also performs a historical review and includes an overview of the contemporary developments worldwide.

Mobile Robots Navigation Alejandra Barrera, 2010-03-01 Mobile robots navigation includes different interrelated activities: i) perception as obtaining and interpreting sensory information; ii) exploration as the strategy that guides the robot to select the next direction to go; iii) mapping involving the construction of a spatial representation by using the sensory information perceived; iv) localization as the strategy to estimate the robot position within the spatial map; v) path planning as the strategy to find a path towards a goal location, being optimal or not; and vi) path execution where motor actions are determined and adapted to environmental changes. The book addresses those activities by integrating results

from the research work of several authors all over the world Research cases are documented in 32 chapters organized within 7 categories next described

Autonomous Mobile Robots: Control, planning, and architecture S. Sitharama Iyengar,Alberto Elfes,1991

Mobile Intelligent Autonomous Systems Jitendra R. Raol,Ajith K. Gopal,2016-04-19

Going beyond the traditional field of robotics to include other mobile vehicles this reference and recipe book describes important theoretical concepts techniques and applications that can be used to build truly mobile intelligent autonomous systems MIAS With the infusion of neural networks fuzzy logic and genetic algorithm paradigms for MIAS it blends modeling sensors control estimation optimization signal processing and heuristic methods in MIAS and robotics and includes examples and applications throughout Offering a comprehensive view of important topics it helps readers understand the subject from a system theoretic and practical point of view

Use of AI, Robotics and Modelling tools to fight Covid-19 Arpit Jain,Abhinav Sharma,Jianwu Wang,Mangey Ram,2022-09-01

The COVID 19 pandemic has hit the global at a colossal scale With worldwide reported cases of 5 34 million it has led to severe impact on humanity Being a highly contagious disease it has given global health services their most severe challenge Various countries are fighting to minimize the losses due to the outbreak however a common trait is enforcing lockdown which has become the main defence mechanism Researchers are working around the clock to find a breakthrough in the diagnostics and treatment of the pandemic AI technology is useful for fast drug development and treatment In the starting phase of COVID 19 pandemic the medical fraternity in China diagnosed the virus using computed tomography CT and X ray images due to the limitation of testing kits Deep learning neural network model have also been used for COVID 19 diagnosis AI assisted intelligent humanoid robots can be used to reduce the human contact and spread of COVID 19 In Italy robots have been used for measuring blood pressure oxygen saturation and temperature of patients Robots have also found applications in disinfecting and sterilizing of public places COVID 19 testing food and medicine delivery as well as entertaining patients in hospitals and quarantine centers thereby reducing the workload of doctors and nurses Prediction of the spread of virus and providing the guidelines or prevention measures is another AI application in COVID 19 Kaggle and GitHub are the two websites where the real time data of COVID 19 is aggregated This includes confirmed cases active cases cured cases and deaths in each country This data set can be used for predicting the active cases across different regions of the world so that appropriate amount of health infrastructure can be made available to these places

Advances in Robot Navigation Alejandra Barrera,2011-07-05

Robot navigation includes different interrelated activities such as perception obtaining and interpreting sensory information exploration the strategy that guides the robot to select the next direction to go mapping the construction of a spatial representation by using the sensory information perceived localization the strategy to estimate the robot position within the spatial map path planning the strategy to find a path towards a goal location being optimal or not and path execution where motor actions are determined and adapted to environmental changes This book integrates results from the research work of authors all over

the world addressing the abovementioned activities and analyzing the critical implications of dealing with dynamic environments Different solutions providing adaptive navigation are taken from nature inspiration and diverse applications are described in the context of an important field of study social robotics **Mobile Robots** ,1995 IROS '93 ,1993
 MFI2003 ,2003 *The Proceedings of the Third IEEE Conference on Control Applications* IEEE Control Systems Society,1994 The Proceedings of the Third IEEE Conference on Control Applications, August 24th-26th, 1994, Venue, the University of Strathclyde, Glasgow, Scotland, UK IEEE Control Systems Society,1994 Optomechatronic Systems ,2003
 Conference on Intelligent Robotics in Field, Factory, Service and Space (CIRFFSS 1994), Volume 2 ,1994
 Autonomous Mobile Robots: Perception, mapping, and navigation Sundararaja S. Iyengar,Alberto Elfes,1991
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Table of Contents Active Sensors For Local Planning In Mobile Robotics

1. Understanding the eBook Active Sensors For Local Planning In Mobile Robotics
 - The Rise of Digital Reading Active Sensors For Local Planning In Mobile Robotics
 - Advantages of eBooks Over Traditional Books
2. Identifying Active Sensors For Local Planning In Mobile Robotics
 - Exploring Different Genres
 - Considering Fiction vs. Non-Fiction
 - Determining Your Reading Goals
3. Choosing the Right eBook Platform
 - Popular eBook Platforms
 - Features to Look for in an Active Sensors For Local Planning In Mobile Robotics
 - User-Friendly Interface
4. Exploring eBook Recommendations from Active Sensors For Local Planning In Mobile Robotics
 - Personalized Recommendations

- Active Sensors For Local Planning In Mobile Robotics User Reviews and Ratings
- Active Sensors For Local Planning In Mobile Robotics and Bestseller Lists
- 5. Accessing Active Sensors For Local Planning In Mobile Robotics Free and Paid eBooks
 - Active Sensors For Local Planning In Mobile Robotics Public Domain eBooks
 - Active Sensors For Local Planning In Mobile Robotics eBook Subscription Services
 - Active Sensors For Local Planning In Mobile Robotics Budget-Friendly Options
- 6. Navigating Active Sensors For Local Planning In Mobile Robotics eBook Formats
 - ePub, PDF, MOBI, and More
 - Active Sensors For Local Planning In Mobile Robotics Compatibility with Devices
 - Active Sensors For Local Planning In Mobile Robotics Enhanced eBook Features
- 7. Enhancing Your Reading Experience
 - Adjustable Fonts and Text Sizes of Active Sensors For Local Planning In Mobile Robotics
 - Highlighting and Note-Taking Active Sensors For Local Planning In Mobile Robotics
 - Interactive Elements Active Sensors For Local Planning In Mobile Robotics
- 8. Staying Engaged with Active Sensors For Local Planning In Mobile Robotics
 - Joining Online Reading Communities
 - Participating in Virtual Book Clubs
 - Following Authors and Publishers Active Sensors For Local Planning In Mobile Robotics
- 9. Balancing eBooks and Physical Books Active Sensors For Local Planning In Mobile Robotics
 - Benefits of a Digital Library
 - Creating a Diverse Reading Collection Active Sensors For Local Planning In Mobile Robotics
- 10. Overcoming Reading Challenges
 - Dealing with Digital Eye Strain
 - Minimizing Distractions
 - Managing Screen Time
- 11. Cultivating a Reading Routine Active Sensors For Local Planning In Mobile Robotics
 - Setting Reading Goals Active Sensors For Local Planning In Mobile Robotics
 - Carving Out Dedicated Reading Time
- 12. Sourcing Reliable Information of Active Sensors For Local Planning In Mobile Robotics
 - Fact-Checking eBook Content of Active Sensors For Local Planning In Mobile Robotics

- Distinguishing Credible Sources
- 13. Promoting Lifelong Learning
 - Utilizing eBooks for Skill Development
 - Exploring Educational eBooks
- 14. Embracing eBook Trends
 - Integration of Multimedia Elements
 - Interactive and Gamified eBooks

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