



CONTROLLABILITY OF TEMPERED CAPUTO FRACTIONAL DYNAMICAL SYSTEMS

MOHAMMAD AYMAN-MURSALEEN

ABSTRACT. In this article, we explored the controllability of fractional dynamical systems with tempered Caputo fractional derivative (FD). We develop the necessary and sufficient conditions for the solution representation of controllability of linear dynamical system involving tempered Caputo FD by utilizing the Gramian matrix. We use Schauder's fixed point theorem to establish sufficient conditions for the controllability of nonlinear fractional dynamical systems involving tempered Caputo FD. The theoretical results are validated through numerical example obtained using successive approximation techniques.

1. INTRODUCTION AND PRELIMINARIES

Over the past three decades, *fractional calculus* has emerged as an advanced branch of mathematical analysis dealing with differentiation and integration of non-integer orders. This field provides a robust framework for modeling complex systems that exhibit nonlinear dynamics, such as those found in physics, engineering, and economics [5, 13, 28]. For instance, Baleanu et al. [12] developed a fractional model of Caputo-type to study the dynamics of the COVID-19 pandemic and to explore its fundamental behaviors.

In the domain of fractional derivatives (FDs), various types are employed to account for memory effects. Over the past decade, experts in dynamical systems theory have utilized a variety of FDs [31]. The most frequently applied FDs in literature are the Caputo and Riemann-Liouville derivatives, both characterized by a singular kernel. To address this limitation, the Caputo-Fabrizio FD was introduced, which features a nonsingular kernel and operates locally. Later, the Atangana-Baleanu FD was proposed as a novel derivative with both nonsingular and nonlocal properties.

Controllability is a key concept in control theory, signifying the ability to steer a dynamical system from any given initial state to a target final state using an appropriate set of controls. The controllability of nonlinear systems in finite-dimensional spaces has been extensively studied, often through the use of fixed-point theorems [9, 23]. Several researchers [10, 11, 14, 20, 21] have derived controllability results for both linear and nonlinear fractional dynamical systems, using tools such as the Gramian matrix and the rank condition. Recently, Vishnukumar et al. [32] investigated the controllability of fractional dynamical systems with a single delay in the

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Controllability Of Dynamical Systems

Peter Chen, Victor Martinez-Luaces



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The Dynamics of Control Fritz Colonius,Wolfgang Kliemann,2000-04-20 This new text reference is an excellent resource for the foundations and applications of control theory and nonlinear dynamics All graduates practitioners and professionals in control theory dynamical systems perturbation theory engineering physics and nonlinear dynamics will find the book a rich source of ideas methods and applications With its careful use of examples and detailed development it is suitable for use as a self study reference guide for all scientists and engineers

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that must be met in order to control a dynamical system in an optimal fashion The theory of optimal feedback control is used as an approach to the dynamics of a mass point in general relativity The theory of reachability with feedback control is also used as an approach to geometrical optics in the frame of general relativity The final chapter describes a system theoretic framework for the study of Hamiltonian systems with external forces This monograph is intended primarily for researchers and graduate students in theoretical physics mechanics control and system theory and mathematics It may also be read profitably by philosophers of science and to some extent by those who have a keen interest in basic questions of contemporary mechanics and physics and who possess some background in the physical and mathematical sciences

Controllability and Minimum Energy Control Jerzy Klamka,2018-06-01 The book offers a comprehensive overview of controllability problems and minimum energy control for broad classes of dynamical systems including linear semilinear and nonlinear systems which are important for modeling systems in automatic control electrical engineering mechanics and informatics It develops the theory of controllability for both finite and infinite dimensional dynamical systems described by differential state equation and studies in detail functional analysis and matrix algebra which provide essential and effective tools for the new solutions of a number of important controllability problems The theoretical results are illustrated by examples throughout the book Primarily intended for academic researchers working in mathematical control theory the self contained text is easily accessible and particularly interesting for control engineering and applied mathematics graduates

Controllability of Discrete Dynamical Systems Trupti P. Shah,2013 This book is very useful to research students who work in the field of Control theory Controllability problems and stability problems of some linear and nonlinear discrete time systems are investigated To obtain Controllability results the tools from analysis such as fixed point theorem inverse function theorem implicit function theorems etc are used Along with controllability results a computational algorithm for the actual computation of steering control is discussed

Controllability, Stabilization, and the Regulator Problem for Random Differential Systems Russell Johnson,Mahesh G. Nerurkar,1998 This volume develops a systematic study of time dependent control processes The basic problem of null controllability of linear systems is first considered Using methods of ergodic theory and topological dynamics general local null controllability criteria are given Then the subtle question of global null controllability is studied Next the random linear feedback and stabilization problem is posed and solved Using concepts of exponential dichotomy and rotation number for linear Hamiltonian systems a solution of the Riccati equation is obtained which has extremely good robustness properties and which also preserves all the smoothness and recurrence properties of the coefficients Finally a general version of the local nonlinear feedback stabilization problem is solved Representation and Control of Infinite Dimensional Systems Alain Bensoussan,Giuseppe Da Prato,Michel C. Delfour,Sanjoy K.

Mitter,2007-04-05 This unified revised second edition of a two volume set is a self contained account of quadratic cost optimal control for a large class of infinite dimensional systems The original editions received outstanding reviews yet this

new edition is more concise and self contained New material has been added to reflect the growth in the field over the past decade There is a unique chapter on semigroup theory of linear operators that brings together advanced concepts and techniques which are usually treated independently The material on delay systems and structural operators has not yet appeared anywhere in book form

Modelling and Control of Dynamical Systems: Numerical Implementation in a Behavioral Framework Ricardo Zavala Yoe, 2008-05-30 The Behavioral Approach for systems and control deals directly with the solution of the differential equations which represent the system This book reviews this approach and offers new theoretic results The programs and algorithms are MATLAB based

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Tautological Control Systems Andrew D. Lewis, 2014-07-22 This brief presents a description of a new modelling framework for nonlinear geometric control theory The framework is intended to be and shown to be feedback invariant As such Tautological Control Systems provides a platform for understanding fundamental structural problems in geometric control theory Part of the novelty of the text stems from the variety of regularity classes e g Lipschitz finitely differentiable smooth real analytic with which it deals in a comprehensive and unified manner The treatment of the important real analytic class especially reflects recent work on real analytic topologies by the author Applied mathematicians interested in nonlinear and geometric control theory will find this brief of interest as a starting point for work in which feedback invariance is important Graduate students working in control theory may also find Tautological Control Systems to be a stimulating starting point for their research

Control of Nonlinear Dynamical Systems Felix L. Chernous'ko, I. M. Ananievski, S. A. Reshmin, 2008-09-26 This book is devoted to new methods of control for complex dynamical systems and deals with nonlinear control systems having several degrees of freedom subjected to unknown disturbances and containing uncertain parameters Various constraints are imposed on control inputs and state variables or their combinations The book contains an introduction to the theory of optimal control and the theory of stability of motion and also a description of some known methods based on these theories Major attention is given to new methods of control developed by the authors over the last 15 years Mechanical and electromechanical systems described by nonlinear Lagrange s equations are considered General methods are proposed for an effective construction of the required control often in an explicit form The book contains various techniques including the decomposition of nonlinear control systems with many degrees of freedom piecewise linear feedback control based on Lyapunov s functions methods which elaborate and extend the approaches of the

conventional control theory optimal control differential games and the theory of stability The distinctive feature of the methods developed in the book is that the controls obtained satisfy the imposed constraints and steer the dynamical system to a prescribed terminal state in finite time Explicit upper estimates for the time of the process are given In all cases the control algorithms and the estimates obtained are strictly proven *Nonlinear and Optimal Control Systems* Thomas L.

Vincent, Walter J. Grantham, 1997-06-23 Designed for one semester introductory senior or graduate level course the authors provide the student with an introduction of analysis techniques used in the design of nonlinear and optimal feedback control systems There is special emphasis on the fundamental topics of stability controllability and optimality and on the corresponding geometry associated with these topics Each chapter contains several examples and a variety of exercises

Journal of Dynamic Systems, Measurement, and Control, 1993 *Nonlinear Systems and Matrix Analysis - Recent Advances in Theory and Applications* Peter Chen, Victor Martinez-Luaces, 2024-11-27 Nonlinear system analysis is of interest to engineers sociologists physicists mathematicians and many other scientists since most systems are inherently nonlinear in nature In mathematics a nonlinear system does not satisfy the superposition principle such as in a linear system Therefore the theories underlining nonlinear analysis and their applications need to be developed on their own merit The first section of this book is a collection of examples reporting recent advances in both theory and applications of nonlinear system analysis The contents of each chapter will provide in depth foresight to interested readers As numerical linearization to a set of matrix equations is still the principal method used to solve a nonlinear system matrix analysis is the topic of the second section of this book The matrices have invaded practically all areas of mathematics the experimental and social sciences engineering and technology This volume updates purely mathematical theoretical aspects and it also presents concrete examples of the wide range of applications of matrix theory in other disciplines **Control Problems of Discrete-Time Dynamical**

Systems Yasumichi Hasegawa, 2015-01-20 This monograph deals with control problems of discrete time dynamical systems which include linear and nonlinear input output relations In its present second enlarged edition the control problems of linear and non linear dynamical systems will be solved as algebraically as possible Adaptive control problems are newly proposed and solved for dynamical systems which satisfy the time invariant condition The monograph provides new results and their extensions which can also be more applicable for nonlinear dynamical systems A new method which produces manipulated inputs is presented in the sense of state control and output control To present the effectiveness of the method many numerical examples of control problems are provided as well IUTAM Symposium on Optimization of Mechanical

Systems D. Bestle, Werner Schiehlen, 2012-12-06 The International Union of Theoretical and Applied Mechanics IUTAM initiated and sponsored an International Symposium on Optimization of Mechanical Systems held in 1995 in Stuttgart Germany The Symposium was intended to bring together scientists working in different fields of optimization to exchange ideas and to discuss new trends with special emphasis on multi body systems A Scientific Committee was appointed by the

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